





# PNEUMATIC DRIVES

# **DRIVES FOR THE SPECIALIST**



# SYSTEM CONCEPT

# FUNCTION

The main air supply (1) is connected to the 4/3-way motor control valve (2) and the hand-operated valve (3).

Pressing the push button (3a) on the hand-operated valve (3), the motor control valve (2) is actuated - the control piston (2a) opens the air way to the motor (4), dual stop valve (5) and the disc brake (6).

The air brake piston (6a) releases the brake disc and the motor (4) is rotating.

When the push button (3a) is released, the control piston (2a) reverts to its initial position, as shown in (2b), and bleeds the brake (6) and the motor (4) via the two lines (bled middle position).

The brake is locked through spring resistance.

If the air supply fails, the brake locks and the motor stops.



# **POWER / TORQUE**

1. The design, the working pressure and the air consumption determin the power and the torque.

At operating pressure, the rotating speed is adjusted accordingly with the released torque.

<u>Example: 6 bar</u>			
Torque	M =	10	Nm
Speed	n =	500	rpm

Optimum operating point approx. half of idling speed.



2. Reducing the operating pressure the performance curve is changed.

Other speeds can only be set by changing the air pressure.

<u>Example: 4 bar:</u>			
Torque	M =	10	Nm
Speed	n = 3	350	rpm



 The torque automatically adjusts to the load. Low loads permits high rotation speed, while the required and produced torque is low. If the load increases, the required torque increases too and the speed lowers.





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# SYSTEM CONCEPT

# **MODULAR SYSTEM**

Our modular system allows multiple combinations of pneumatic gear drives.

# CONTROL



Connection for clockwise or anti-clockwise rotation: - non-reversible



Remote control: - pilot operated - reversible



Hand lever control: - reversible



Remote control: - direct - reversible



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## **VANE-TYPE MOTORS**

Our pneumatic vane-type motors are available with the following options:

- Direction of rotation right
- Direction of rotation left
- Direction of rotation reversible
- Power from 0.2 kW up to 10.0 kW
- With flange mounting
- With foot mounting
- With brake
- Without brake
- Shaft (with feather key or threaded)

Please ask for output charts and data sheets separately.

### CONTROLS

#### Non-reversible motors:

For non-reversible motors you select the direction of rotation, i.e. clockwise or anti-clockwise (looking in front of the motor to the shaft).

#### With reversible motors, you choose between:

#### 1) Hand lever control

The reversing valve is mounted directly on the motor. The reversing mechanism in the valve can be provided by a rotary valve, piston slide or two differential pistons.

#### 2) Direct remote control

There is no actuating mechanism attached to the motor. The operating air is fed directly to the motor via two main air connections. Actuation is performed by a 4/3-way control slide.

#### 3) Pilot-operated remote control

The main reversing valve attached to the motor housing is first actuated by one or two small pilot valves, setting the motor to the required direction of rotation.

### **GEARS**

The fields of application for motors increase by using gears. Spur gears, single- and multiple-speed planetary gears with variants i=2 up to i=350 are standard.

### **BRAKES / END COVERS**

The locked disc brake is unlocked with compressed air and closes as result of spring resistance when the air supply is shut off or fails.

Mounting and shaft dimensions can be customized - if the constructive design permits.

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# SYSTEM CONCEPT



Type with or without brake



Direct hand lever control or pilot-operated remote control

**ATEX-Safety class** 

approved



**Customized output shaft** 

Robust vane-type motor with drive power from 0.2 up to 10.0 kW



1-800-700-5919 (US/CA)

Foot adapter plate or flange adapter type



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Spur gears or planetary gears with i=2 up to 350



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### **SPECIAL FEATURES**

- The pneumatic vane-type motors are **robust**, **compact** and **usable** in a wide range of applications.
- They are not sensitive to dirt, moisture, temperature fluctuations or overloading.
- The pneumatic vane-type motors are **fully enclosed**. Ambient air, often infiltrated with dust and dirt, cannot penetrate the motors.
- There is no need for an additional supply of cooling air.
  Cooling is performed by the decompression of the operating air.
  During the rotation of the motor the compressed air expands and cools the motor.
- Due to the special design of the vane-type motors, they can also be **used under extreme conditions**, such as under water.
- **Overload causes no damage**. Once the overload is reduced, they starts again.
- The motors can be operated with **compressed air** or other **compressed gasses**.
- The vane motors can be adjusted for a **large speed range** by simply throttling the air volume and working pressure.
- Fail safe disc brakes are possible to built in for almost all motors.
- All pneumatic vane-type motors operate **spark-free** and are thus suitable for use in **hazardous environment**.
- ATEX conform.

## ACCESSORIES

Accessories like hand control valves, pilot valves, oilers, service units, etc. will be individually combined with your pneumatic drive.



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# TECHNICAL DEMANDS

## QUESTIONNAIRE

Please answer the questions as comprehensively as possible and sketch and mark the most important dimensions.

After receiving your request we will quote the right pneumatic drive to you.

The e-questionnaire is on www.spitznas.de/en/drives/pneumatic/questionnaire/

Additionally you can upload sketches, photos etc.

Company		Date	:	
Name	Departm	ent: Phone	:	
Street		Fax	:	
Country	· ·	E-Mail	:	@

1. Intended use (desription of purpose as complete as possible):

2.	Quantity required			Single motor	:	
				Series	: 🗆	
				Quantity	:	Units
				Test model	:	
3.	Required characteristics			Power		kW
				Torque	:	Nm
				Speed under load		rpm
				Max. free speed		rpm
4.	Type of load on motor (e.g. st	arting up under full	load)	Starting torque	:	Nm
5.	Flow pressure at motor conn	ection		p		bar
6.	Connection (inside diameter of	connection hose)		Hose I/D	:	mm
				Pipe conduit inside		inches
7.	Direction of rotation (looking f	rom front at the sha	aft end) Right- ha	and rotation (clockwise)		
			Left- hand r	otation (anti- clockwise)		
				Reversible		
8.	3. Type of control Hand-lever on motor (direct control):					
	Remote control, pilot controlled:				:	
	Remote control, direct via 2 connecting lines:				: 🗆	
9.	Mounting	Thread mounting	:	Foot mounting	:	
		Special mounting	: 🗆	Flange mounting		
10.	Design of motor			with brake	:	
				without brake	: []	
11.	Output shaft (e.g. shaft butt, to	othing, square):			_	
12.	Lubrication (if requested)			Service unit	: 🗌	
	Line oiler for horizontal or vertical installation:					
13.	Do any special regulations co	ncerning maximu	m permissibile s	ound level exist? yes	: 🗌	
	If yes, which?			no	:	
				max. noise level		dB(A)
14.	Other information:					
	-				_	
15.	Do you have enclosed a ske	tch? yes	: page(s)	no	: []	

# HYDRAULIC DRIVES PROGRAM



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